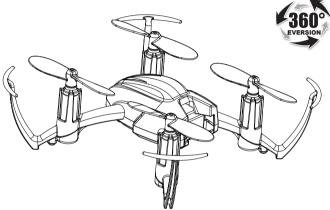


2.4G 4 CH REMOTE CONTROL QUADCOPTER





INSTRUCTION MANUAL

IMPLEMENT STANDARD: GB/T26701-2011

Main characteristics

- Four-axis structure is applied, which makes the quadcopter more flexible and rapid when flying. It has the characteristics of wind-resistant and can be flied indoor or outdoor.
- Built-in gyroscope stabilizer can ensure accurte positing in the air.
- Modular design structure is applied, more simple for assembly and convenient for maintenance.
- 360 degree 3D stunt & tumbling function.

All material, dimensions and spare parts included in this instruction are for reference only. The company is not responsible for any changes printed parts and notify consumer. Any updated or changed please refer to our website www.symatoys.com.

PREFACE

Dear customers:

Hello!

Thank you for purchasing our flying model. Please read this instruction manual carefully in order to master the skill required in order to master the skill more quickly and operate this product more safely. In the mean time, please well keep the original of this instruction manual for future reference.

IMPORTANT INSTRUCTION

- 1. This product is not a toy but one precisive equipment that integrating mechanics and electronics with expertise of aerodynamics and high-frequency transmitting. It requires to be correctly assembled and debugged so as to prevent the accident from being happened. The product owner should operate or control it in safe way. Please noted that we won't take any responsibility for any wrong operation as this may result in severe injury or loss of property and we can not control the operating process during the time when the user assemble or use this product.
- 2.This product is suitable to be used by people who has operating experience in flying model or age no less than 14 years old.
- 3. The flying ground we required should be the local field and legal for remote control flying.
- 4.Once this product is sold , we won't be responsible for any safety responsibility during the time the user operates or uses or controls this product.
- 5. If there is any problem occurred during the time of using, operating or repairing, please reach our sales agent for details. The sales agent that we authorized will provide you with the technical support and after-sale service.

SAFETY & CAUTIONS

This R/C flying model is one high dangerous commodity. Please make sure that it should be flied far away from the crowd. Please also pay more attention to the phenomenon such as incorrect assembly or damaged model or incorrect connection of electronic control equipment. Please also pay attention to the flying safety when operating and know more about the accident that may be happened due to your own negligence.

- 1. Keep it far away from the barrier or crowd.
- 2.Keep it far away from the moisten environment.
- 3. Use this product correctly and avoid operating by your own.
- 4. Keep it far away from the high-speed rotating part and heat source.
- 5. Please conform to the sequence of power ON/OFF.As the picture below shown, incorrect sequence of power ON/OFF may cause this product out of control and affect your own safety or others. Please form a good habit of switching on or switching off this product correctly.

ABOUT CONTENTS

Product included following contents:

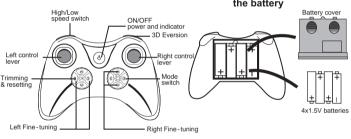
- Quadcopter
- 2.4G Remote controller
- USB charging wire
- Instruction manual
- Screwdriver
- Blade(4 pieces)



GET TO KNOW YOUR TRANSMITTER

Introduction of transmitter

Remote control Installing the battery

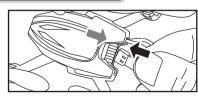


Open the back cover at the back of the transmitter. Load 4PCS "AA" alkaline batteries correctly into the battery compartment as per the correct polarity shown on the battery compartment.

READY TO FLY YOUR QUADCOPTER



Step 1: First of all, press the ON/OFF power switch.



Step 2: Insert the power wire into the quadcopter and place it on the level ground.



Step 3: Push the throttle lever to the highest position and then pull it back to the lowest position,this time there will be one clear sound sending out from the transmitter,this shows that the quad copter has entered into the pre-fly state.

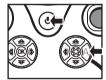


TIPS: When matching signal, keep the quadcopter on horizontal position to fast matching and start a stable flight.

CAUTIONS

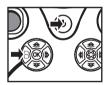
- 1. When the indicator of the transmitter appears eternal bright, however, the indicator of the quadcopter appers slow flashing, this means that decoding is not successful. This time please disconnect the power both of the quad copter and transmitter, then repeat the pre-flying steps.
- 2.If the quadcopter is tilting to one side abruptly or spining while hoveing, please switch off the power both of the quadcopter and transmitter and then repeat the pre-flying steps.
- 3.When the indicator of the quadcopter keeps flashing slowly, it means that the quad copter has entered into the low voltage protection state. This time you need to charge the quadcopter.

MODE SWITCH & TRIMMING RESET FUNCTION



Mode swith function:

Keep pressing the button A, then switch on the power of the transmitter, your can select Mode 1 or Mode 2.



Resetting function:

Keep pressing the button B, then switch on the power of thetransmitter. Enter into the Trimming &Resetting Mode(It is highly suggested that the freshman should reset the trummer first before starting the first flight.)

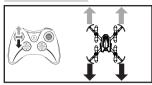


Level calibration function:

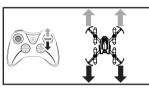
If quadcopter always fly to a side when starting, please re-match signal and place it on a horizontal plane. Than turn the two levers to the lower right comer(as left image) for seconds, when indicator keep light up, it finshes auto level calibration

ILLUSTRATION ON CONTROLL THE QUADCOPTER (MODE 1, DEFAULTED MODE WHEN STARTING)

Operating direction



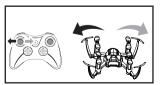
Push the throttle up or down, the quad copter flies upward or downward.



Push the direction lever up or down, the quadcopter flies forward or backward.



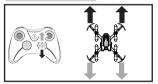
Pull the direction lever left or right, the quadcopter flies to left side or right side.



Pull the throttle left or right, the quadcopter turns to left or right.



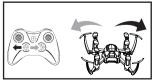
Fine-tuning operation



When the quadcopter keeps flying forward / backward, you can correct it by pressing under / top fine-tuning button.



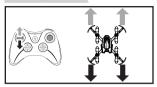
When the quadcopter keeps flying to left / right side, you can correct it by pressing the right / left fine-tuning button.



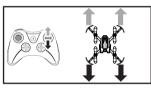
When the quadcopter keeps rotating to left / right, you can correct it by pressing the left / right fine-tuning button.

ILLUSTRATION ON HOW TO CONTROL THE QUADCOPTER (MODE 2)

Operating direction



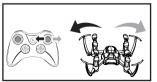
Push the throttle up or down, the quad



Push the direction lever up or down, the quadcopter flies forward or backward.



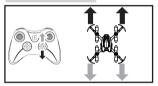
Pull the throttle left or right, the quadcopter flies to left side or right side.



Pull the direction lever left or right, the quad copter turns to left or right.



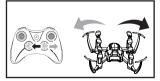
Fine-tuning operation



When the quadcopter keeps flying forward / backward, you can correct it by pressing under / top fine-tuning button.



When the quadcopter keeps flying to left / right side, you can correct it by pressing the right / left fine-tuning button.

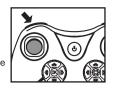


When the quadcopter keeps rotating to left / right, you can correct it by pressing the left / right fine-tuning button.

FLIGHT CONTROL

Low Speed: Press the High/Low speed switch for one time, the buzz will send out one sound.

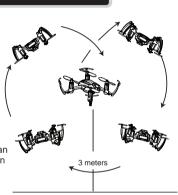
High Speed: Please press High/Low speed switch once again, the buzz will send out two sounds.



3D EVERSION AND THROWING FLIGHT INSTRUCTIONS

1.When you are familiar with the basic operation, you can play some awesome & thrilling stunt operation. First of all, fly the four-axial aircraft to the height of about or more than 3 meters, press the 3D Eversion switch on the right above of the transmitter, then right above of the transmitter, and push the right rudder (in any direction) at the same tone then you can make 360 degree 3D tumbling operation in any direction and make successive

tumbling stunt performance as well.



2.Using 6 axis gyroscope, quadcopter bring you more fun. Throw out the quadcopter or push up throttle lever when it rolling, the quadcopter could hover smoothly in the sky.



BATTERY CHARGING

Battery charging

Take out the USB charging wire, connect one end to the quadcopter, then insert the USB port of the USB charging wire to the USB port of the computer (or the USB port of the power adapter) to charge the battery. During the time of charging, the red indicator of the USB will be ON.

When it is fully charged, the red indicator will be OFF.

Caution:

- Please pull out the charging wire before shutting down the computer when charging by the computer.
- Please make sure the polarity connecting is correctly when connecting the USB wire to the battery ,and make sure the polarity can not be upside or down.



Charging time: about 30 minutes; Flying time: about 5 minutes.

CAUTIONS WHEN CHARGING

- When charging, please put this product on the dried or ventilated area and keep it far away from heat source or explosive product.
- 2.When charging, please remove the batteries from the quad copter.All the charging process should be under the guidance of the adult so as not to cause accident.
- 3.When finish flying, please do not charge the battery which surface temperature is still not cooled down.Otherwise it may cause swollen battery or even cause fire disaster.
- 4. During the process of battery charging, falling down or striking by the outer force should be avoided. Otherwise it may cause short-circuited within the battery and thus may cause danger.
- 5.In order to make sure safety, please make sure that you need to use the original USB charging wire that made from our factory. When the battery is used for a long time or appears aging or swollen, please replace them timely.
- 6.When the batteries are fully charged, if you do not remove it from the charger for a long time, the battery may discharge automatically, which may cause battery exhaustion. When the battery voltage that the charger has tested is lower than the rated voltage, the charger will re-charge the battery until it is fully charged. Charging or discharging too often or repeated charging or discharging may reduce the using life of the batteries.

BATTERY REPAIR & MAINTENANCE

- 2.In order to enhance the using life of the battery, please avoid repeat charging or excessive discharging.
- 3.When the battery needs to be stored for a long time, please charge the battery first. That is to say, charge the battery for about 50-60% of the volume and then well store it.
- 4.If you do not use it for more than 1 months, it's highly recommended that you need to check the battery voltage every month so as to make sure the voltage no less than 3V. Otherwise please do by following No.(3) mentioned.

TROUBLE SHOOTING

Symptom	Reason	Troubleshooting			
No response from the aircraft	Matching freguency is not successfully made. Insufficient power with the aircraft or transmitter.	1.Re-Matching: First of all, switch on the power of the transmitter, then switch on the power of the aircraft and place it on the level ground, finally pushing the throttle lever to the highest and then pull it back to the starting position. 2.Replace the battery of the transmitter or charge the aircraft.			
The reaction of aircraft is not smart or intermitting signal.	I.Insufficient power with the transmitter. Antenna of the aircraft is snapped off.	1.Replace the batteries inside the transmitter. 2.Re-welding the antenna.			
The aircraft can not make hovering or tilt flying to one side.	The aircraft is not placed on the level ground when Matching freguency. The trimmer key on the transmitter is not reset.	Re-Matching freguency. Reset the trimmer key on the transmitter, details please kindly check Page3 Functional Adjusting of Flying Resetting.			

TROUBLE SHOOTING

All the sare parts below can bought from local distributor.



X2-01A Upper body-Red



X2-01B Upper body-Black



X2-02A Lower body-Red



X2-02B



X2-03 Blades



X2-04 Motor A



X2-05 Motor B



X2-06 Battery



Circuit board

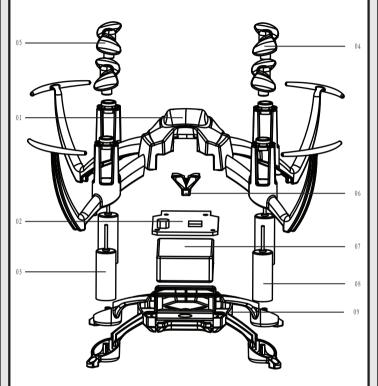


USB charger wire



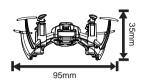
X2-09 Transmitter

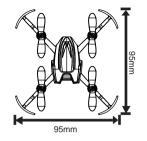
BREAKDOWN & DIAGRAM



Code	Description	Quantity	Code	Description	Quantity	Code	Description	Quantity
01	Upper body	1	04	Rotating blade	2	07	Battery	1
02	Receiver board	1	05	Reversing blade	2	08	Receiver motor	2
03	Rotating motor	2	06	Transparent piece	1	09	Lower body	1

MAIN PARAMETER





Length of fuselage: 95mm

Code of main engine: Ø6

Width of fuselage: 95mm

Battery: 3. 7V/150mAh

Height of fuselage: 35mm







SPECIFICATIONS AND COLORS OF CONTENTS MAY VARY FROM PHOTO.

